# T-coercivity: a practical tool for the study of variational formulations 

## Patrick Ciarlet

POEMS, ENSTA Paris, Institut Polytechnique de Paris, France


ENSTA
IP PARIS

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## Outline

(1) What is T-coercivity?
(2) Stokes model
(3) Neutron diffusion model
(4) Further remarks
(5) Conclusion

## What is T-coercivity?

A tool to study variational formulations

Abstract framework: Find $u \in V$ s.t. $\forall w \in W, a(u, w)=W^{\prime}\langle f, w\rangle_{W}$. Approximate framework: Find $u_{\delta} \in V_{\delta}$ s.t. $\forall w_{\delta} \in W_{\delta}, a\left(u_{\delta}, w_{\delta}\right)=W^{\prime}\left\langle f, w_{\delta}\right\rangle_{W}$.

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(1) First, analyse the variational formulation theoretically:

- prove well-posedness;
- existence, uniqueness and continuous dependence of the solution with respect to the data.


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(2) Second, solve the variational formulation numerically:
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Within the framework of T-coercivity, steps 1 and 2 are very strongly correlated!

## What is T-coercivity?

## As an abstract tool

Let

- $V, W$ be Hilbert spaces;
- $a(\cdot, \cdot)$ be a continuous sesquilinear form on $V \times W$;
- $f$ be an element of $W^{\prime}$, the dual space of $W$.

Solve

$$
\text { (VF) Find } u \in V \text { s.t. } \forall w \in W, a(u, w)=W^{\prime}\langle f, w\rangle_{W}
$$

[Banach-Nečas-Babuška] The inf-sup condition writes

$$
\text { (isc) } \exists \alpha>0, \forall v \in V, \sup _{w \in W \backslash\{0\}} \frac{|a(v, w)|}{\|w\|_{W}} \geq \alpha\|v\|_{V} \text {. }
$$

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\text { (VF) Find } u \in V \text { s.t. } \forall w \in W, a(u, w)=W^{\prime}\langle f, w\rangle_{W}
$$

## Definition (T-coercivity)

The form $a(\cdot, \cdot)$ is T-coercive if

$$
\exists \mathrm{T} \in \mathcal{L}(V, W) \text { bijective, } \exists \underline{\alpha}>0, \forall v \in V,|a(v, \mathrm{~T} v)| \geq \underline{\alpha}\|v\|_{V}^{2} .
$$

NB. In other words, the form $a(\cdot, \mathrm{~T} \cdot)$ is coercive on $V \times V$.

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Solve

$$
\text { (VF) Find } u \in V \text { s.t. } \forall w \in W, a(u, w)=W^{\prime}\langle f, w\rangle_{W}
$$

## Theorem (Well-posedness)

The three assertions below are equivalent:
(i) the Problem (VF) is well-posed;
(ii) the form $a(\cdot, \cdot)$ satisfies (isc) and $\{w \in W \mid \forall v \in V, a(v, w)=0\}=\{0\}$;
(iii) the form $a(\cdot, \cdot)$ is T-coercive.

The operator T realises the inf-sup condition (isc) explicitly: $w=\mathrm{T} u$ works!

## What is T-coercivity?

## As an abstract tool (simplified)

Let

- $V$ be a Hilbert space;
- $a(\cdot, \cdot)$ be a continuous, sesquilinear, hermitian form on $V \times V$;
- $f$ be an element of $V^{\prime}$, the dual space of $V$.

Solve
(VF) Find $u \in V$ s.t. $\forall w \in V, a(u, w)={ }_{V^{\prime}}\langle f, w\rangle_{V}$.

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- $V$ be a Hilbert space;
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- $f$ be an element of $V^{\prime}$, the dual space of $V$.

Solve

$$
\text { (VF) Find } u \in V \text { s.t. } \forall w \in V, a(u, w)=V_{V^{\prime}}\langle f, w\rangle_{V}
$$

## Definition (T-coercivity, hermitian case)

The form $a(\cdot, \cdot)$ is T-coercive if

$$
\exists \mathrm{T} \in \mathcal{L}(V), \exists \underline{\alpha}>0, \forall v \in V,|a(v, \mathrm{~T} v)| \geq \underline{\alpha}\|v\|_{V}^{2}
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## What is T-coercivity?

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Let

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## Theorem (Well-posedness, hermitian case)

The three assertions below are equivalent:
(i) the Problem (VF) is well-posed;
(ii) the form $a(\cdot, \cdot)$ satisfies (isc);
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The operator T realises the inf-sup condition (isc) explicitly.

## What is T-coercivity?

As an approximation tool

Let

- $\left(V_{\delta}\right)_{\delta}$ be a family of finite dimensional subspaces of $V$;
- $\left(W_{\delta}\right)_{\delta}$ be a family of finite dimensional subspaces of $W$.

Assume that $\operatorname{dim}\left(V_{\delta}\right)=\operatorname{dim}\left(W_{\delta}\right)$ for all $\delta>0$.
Solve

$$
(\mathrm{VF})_{\delta} \text { Find } u_{\delta} \in V_{\delta} \text { s.t. } \forall w_{\delta} \in W_{\delta}, a\left(u_{\delta}, w_{\delta}\right)=W_{W^{\prime}}\left\langle f, w_{\delta}\right\rangle_{W}
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$$

[Banach-Nečas-Babuška] The uniform discrete inf-sup condition writes

$$
\text { (udisc) } \exists \alpha_{\dagger}>0, \forall \delta>0, \forall v_{\delta} \in V_{\delta}, \sup _{w_{\delta} \in W_{\delta} \backslash\{0\}} \frac{\left|a\left(v_{\delta}, w_{\delta}\right)\right|}{\left\|w_{\delta}\right\|_{W}} \geq \alpha_{\dagger}\left\|v_{\delta}\right\|_{V}
$$

NB. When (udisc) is fulfilled, (VF) ${ }_{\delta}$ is well-posed for all $\delta>0$.

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$$

## Definition (uniform $\mathrm{T}_{\delta}$-coercivity)

The form $a$ is uniformly $\mathrm{T}_{\delta}$-coercive if

$$
\exists \alpha^{\star}, \beta^{\star}>0, \forall \delta>0, \exists \mathrm{~T}_{\delta} \in \mathcal{L}\left(V_{\delta}, W_{\delta}\right),\| \| \mathrm{T}_{\delta} \| \leq \beta^{\star} \text { and } \forall v_{\delta} \in V_{\delta},\left|a\left(v_{\delta}, \mathrm{T}_{\delta} v_{\delta}\right)\right| \geq \alpha^{\star}\left\|v_{\delta}\right\|_{V}^{2} .
$$

NB. When $a$ is uniformly $\mathrm{T}_{\delta}$-coercive, (VF) $)_{\delta}$ is well-posed for all $\delta>0$.

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As an approximation tool

## Let

- $\left(V_{\delta}\right)_{\delta}$ be a family of finite dimensional subspaces of $V$;
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Assume that $\operatorname{dim}\left(V_{\delta}\right)=\operatorname{dim}\left(W_{\delta}\right)$ for all $\delta>0$.
Solve

$$
(\mathrm{VF})_{\delta} \text { Find } u_{\delta} \in V_{\delta} \text { s.t. } \forall w_{\delta} \in W_{\delta}, a\left(u_{\delta}, w_{\delta}\right)={ }_{W^{\prime}}\left\langle f, w_{\delta}\right\rangle_{W}
$$

## Theorem (Convergence)

Assume that the family $\left(V_{\delta}\right)_{\delta}$ fulfills the basic approximability property in $V$.
In addition, assume that
(i) either, the form $a(\cdot, \cdot)$ satisfies (udisc);
(ii) or, the form $a(\cdot, \cdot)$ is uniformly $\mathrm{T}_{\delta}$-coercive.

Then, $\lim _{\delta \rightarrow 0}\left\|u-u_{\delta}\right\|_{V}=0$.

## What is T-coercivity?

Key idea

Use the knowledge on operator T to derive the discrete operators $\left(\mathrm{T}_{\delta}\right)_{\delta}$ !

## What is T-coercivity?

Can be applied to various types of variational formulations
(1) Coercive plus compact formulations. See for instance:

- with integral equations: Buffa-Costabel-Schwab'02 (Thm 7, called $\Theta$-coercivity there), Buffa-Christiansen'03 (Cor. 4.2), Buffa-Christiansen'05 (Prop. 3.7), Buffa'05 (§§3-4).
- with volume equations: Hiptmair’02 (§5, " $(X+S)$-coercivity"), Buffa'05 (§§3-4), PC’ ${ }^{\prime} 12$ (elementary proofs...), book by Sayas-Brown-Hassell (2019) (§15.1).
(2) Formulations with sign-changing coefficients. See for instance:

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- for scalar models: BonnetBenDhia-PC-Zwölf'10, Nicaise-Venel'11,
    BonnetBenDhia-Chesnel-PC'12', Chesnel-PC'13, Carvalho-Chesnel-PC'17,
    BonnetBenDhia-Carvalho-PC'18.
- for EM models: BonnetBenDhia-Chesnel-PC'14` (x2), PC'21
    Abstract T-coercivity only
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(3) Mixed formulations.

- for the Stokes model: see below!
- for diffusion models: Jamelot-PC'13, see below!


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- for EM models: BonnetBenDhia-Chesnel-PC' $14^{\dagger}$ ( $\times 2$ ), PC’ ${ }^{\prime} 21$.
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- for the Stokes model: see below!
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## Stokes model

(1) Let $\Omega$ be a domain of $\mathbb{R}^{3}$. The "simplest" Stokes equations write

$$
\left\{\begin{array}{l}
-\nu \Delta \boldsymbol{u}+\nabla p=\boldsymbol{f} \text { in } \Omega \\
\operatorname{div} \boldsymbol{u}=0 \text { in } \Omega \\
\boldsymbol{u}=0 \text { on } \partial \Omega
\end{array}\right.
$$

for some $\nu>0$ (viscosity).

## Stokes model

(1) Assuming that $\boldsymbol{f} \in\left(\boldsymbol{H}_{0}^{1}(\Omega)\right)^{\prime}$, one analyses mathematically the model
(Stokes) $\quad\left\{\begin{array}{l}\text { Find }(\boldsymbol{u}, p) \in \boldsymbol{H}_{0}^{1}(\Omega) \times L_{z m v}^{2}(\Omega) \text { such that } \\ -\nu \Delta \boldsymbol{u}+\nabla p=\boldsymbol{f} \text { in } \Omega \\ \operatorname{div} \boldsymbol{u}=0 \text { in } \Omega .\end{array}\right.$

## Stokes model

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\operatorname{div} \boldsymbol{u}=0 \text { in } \Omega .
\end{array}\right.
$$

(2) The equivalent variational formulation writes
(FV-Stokes) $\left\{\begin{array}{l}\text { Find }(\boldsymbol{u}, p) \in \boldsymbol{H}_{0}^{1}(\Omega) \times L_{z m v}^{2}(\Omega) \text { such that } \\ \forall(\boldsymbol{v}, q) \in \boldsymbol{H}_{0}^{1}(\Omega) \times L_{z m v}^{2}(\Omega) \\ \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{u}: \nabla \boldsymbol{v} d \Omega-\int_{\Omega} p \operatorname{div} \boldsymbol{v} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{u} d \Omega=\boldsymbol{H}^{-1}(\Omega)\langle\boldsymbol{f}, \boldsymbol{v}\rangle_{\boldsymbol{H}_{0}^{1}(\Omega)} .\end{array}\right.$

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Question: how to prove well-posedness "easily"?

## Stokes model

## The model

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Question: how to prove well-posedness "easily"?

Use T-coercivity for the Stokes model!

## Stokes model

Constructive proof of well-posedness with T-coercivity - 1

Let

- $V=\boldsymbol{H}_{0}^{1}(\Omega) \times L_{z m v}^{2}(\Omega)$, endowed with the norm $\|(\boldsymbol{v}, q)\|_{V}=\left(|\boldsymbol{v}|_{1, \Omega}^{2}+\|q\|^{2}\right)^{1 / 2}$;
- $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$;
${ }^{-}{ }_{V^{\prime}}\langle f,(\boldsymbol{w}, r)\rangle_{V}={ }_{\boldsymbol{H}^{-1}(\Omega)}\langle\boldsymbol{f}, \boldsymbol{w}\rangle_{\boldsymbol{H}_{0}^{1}(\Omega)}-\int_{\Omega} r g d \Omega(g=0$ for Stokes $)$.


## Stokes model

Constructive proof of well-posedness with T-coercivity - 1

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- $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$;
- ${ }_{V^{\prime}}\langle f,(\boldsymbol{w}, r)\rangle_{V}={ }_{\boldsymbol{H}^{-1}(\Omega)}\langle\boldsymbol{f}, \boldsymbol{w}\rangle_{\boldsymbol{H}_{0}^{1}(\Omega)}-\int_{\Omega} r g d \Omega$ ( $g=0$ for Stokes).

The first goal is to prove the inf-sup condition, with the help of T-coercivity. NB. The form $a$ is not coercive, because $a((0, q),(0, q))=0$ for $q \in L_{z m v}^{2}(\Omega)$.

## Stokes model

Constructive proof of well-posedness with T-coercivity - 1

Let

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- $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$;
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The first goal is to prove the inf-sup condition, with the help of T-coercivity. Given $(\boldsymbol{v}, q) \in V \backslash\{(0,0)\}$, we look for $\left(\boldsymbol{w}^{\star}, r^{\star}\right) \in V \backslash\{(0,0)\}$ with linear dependence such that

$$
\left|a\left((\boldsymbol{v}, q),\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right)\right| \geq \alpha\|(\boldsymbol{v}, q)\|_{V}\left\|\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right\|_{V},
$$

with $\alpha>0$ independent of $(\boldsymbol{v}, q)$. In other words, T is defined by $\mathrm{T}((\boldsymbol{v}, q))=\left(\boldsymbol{w}^{\star}, r^{\star}\right)$.

## Stokes model

Constructive proof of well-posedness with T-coercivity - 1

Let

- $V=\boldsymbol{H}_{0}^{1}(\Omega) \times L_{z m v}^{2}(\Omega)$, endowed with the norm $\|(\boldsymbol{v}, q)\|_{V}=\left(|\boldsymbol{v}|_{1, \Omega}^{2}+\|q\|^{2}\right)^{1 / 2}$;
- $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$;
${ }^{-}{ }_{V^{\prime}}\langle f,(\boldsymbol{w}, r)\rangle_{V}={ }_{\boldsymbol{H}^{-1}(\Omega)}\langle\boldsymbol{f}, \boldsymbol{w}\rangle_{\boldsymbol{H}_{0}^{1}(\Omega)}-\int_{\Omega} r g d \Omega(g=0$ for Stokes $)$.
The first goal is to prove the inf-sup condition, with the help of T-coercivity. Given $(\boldsymbol{v}, q) \in V \backslash\{(0,0)\}$, we look for $\left(\boldsymbol{w}^{\star}, r^{\star}\right) \in V \backslash\{(0,0)\}$ with linear dependence such that

$$
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$$

with $\alpha>0$ independent of $(\boldsymbol{v}, q)$. Three steps:
(1) $q=0$;
(2) $\boldsymbol{v}=0$;
(3) General case.

## Stokes model

Constructive proof of well-posedness with T-coercivity - 2
Recall $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$.
(1) $a((\boldsymbol{v}, 0),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$ : so choosing $\left(\boldsymbol{w}^{\star}, r^{\star}\right)=(\boldsymbol{v}, 0)$ yields

$$
\left|a\left((\boldsymbol{v}, 0),\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right)\right|=\nu\|(\boldsymbol{v}, 0)\|_{V}\left\|\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right\|_{V}
$$

## Stokes model

Constructive proof of well-posedness with T-coercivity - 2
Recall $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \nabla \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$.
(1) $a((\boldsymbol{v}, 0),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$ : choose $\left(\boldsymbol{w}^{\star}, r^{\star}\right)=(\boldsymbol{v}, 0)$.
(2) $a((0, q),(\boldsymbol{w}, r))=-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega$ : according to eg. Girault-Raviart' 86 ,
$\exists C_{\text {div }}>0, \forall q \in L_{v m n}^{2}(\Omega), \exists \boldsymbol{w}_{q} \in \boldsymbol{H}_{0}^{1}(\Omega)$ such that $\operatorname{div} \boldsymbol{w}_{q}=q$, with $\left|\boldsymbol{w}_{q}\right|_{1, \Omega} \leq C_{\text {div }}\|q\|$.
So choosing $\left(\boldsymbol{w}^{\star}, r^{\star}\right)=\left(-\boldsymbol{w}_{q}, 0\right)$ yields

$$
\left|a\left((0, q),\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right)\right| \geq\|q\| \frac{\left|\boldsymbol{w}_{q}\right|_{1, \Omega}}{C_{\mathrm{div}}}=\frac{1}{C_{\mathrm{div}}}\|(0, q)\|_{V}\left\|\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right\|_{V} .
$$

## Stokes model

Constructive proof of well-posedness with T-coercivity - 2
Recall $a((\boldsymbol{v}, q),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \nabla \boldsymbol{w} d \Omega-\int_{\Omega} q \operatorname{div} \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$.
(1) $a((\boldsymbol{v}, 0),(\boldsymbol{w}, r))=\nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \nabla \boldsymbol{w} d \Omega-\int_{\Omega} r \operatorname{div} \boldsymbol{v} d \Omega$ : choose $\left(\boldsymbol{w}^{\star}, r^{\star}\right)=(\boldsymbol{v}, 0)$.
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(3) General case: beginning with the linear combination $\boldsymbol{w}^{\star}=\lambda \boldsymbol{v}-\mu \boldsymbol{w}_{q}, \lambda, \mu>0$, one finds

$$
a\left((\boldsymbol{v}, q),\left(\boldsymbol{w}^{\star}, r\right)\right)=\lambda \nu|\boldsymbol{v}|_{1, \Omega}^{2}-\mu \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \boldsymbol{\nabla} \boldsymbol{w}_{q} d \Omega-\int_{\Omega}(\lambda q+r) \operatorname{div} \boldsymbol{v} d \Omega+\mu\|q\|^{2} .
$$

## Stokes model

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(3) General case: $\boldsymbol{w}^{\star}=\lambda \boldsymbol{v}-\mu \boldsymbol{w}_{q}, \lambda, \mu>0$. Next, $r^{\star}=-\lambda q$ leads to

$$
a\left((\boldsymbol{v}, q),\left(\boldsymbol{w}^{\star}, r^{\star}\right)\right)=\lambda \nu|\boldsymbol{v}|_{1, \Omega}^{2}+\mu\|q\|^{2}-\mu \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{v}: \nabla \boldsymbol{w}_{q} d \Omega .
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Finally, the last term can be controlled by the first two terms, using Young's inequality.

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Finally, the last term can be controlled by the first two terms, using Young's inequality. Eg., choose $(\lambda, \mu)=\left(\nu\left(C_{\text {div }}\right)^{2}, 1\right): \mathrm{T}((\boldsymbol{v}, q))=\left(\nu\left(C_{\text {div }}\right)^{2} \boldsymbol{v}-\boldsymbol{w}_{q},-\nu\left(C_{\text {div }}\right)^{2} q\right)$.

## Stokes model

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Finally, the last term can be controlled by the first two terms, using Young's inequality. Eg., choose $(\lambda, \mu)=\left(\nu\left(C_{\text {div }}\right)^{2}, 1\right): \mathrm{T}((\boldsymbol{v}, q))=\left(\nu\left(C_{\text {div }}\right)^{2} \boldsymbol{v}-\boldsymbol{w}_{q},-\nu\left(C_{\text {div }}\right)^{2} q\right)$. NB. Playing with Young's inequality, one finds that there is an "admissible" family of coefficients $(\lambda, \mu)$ that yield T-coercivity.

## Stokes model

Constructive proof of well-posedness with T-coercivity - 3

Regarding the proof with T-coercivity, one can make several observations:
(1) The result of Girault-Raviart' 86 appears as a requirement to derive the inf-sup condition!
(2) The T-coercivity approach is flexible, in the sense that one has at hand a family of operators $T$ (depending on the chosen linear combination). Among others, one may "optimize" the value of the stability constant with respect to $\nu$.
(3) The approach is easily transposed to the approximation, see below!

## Stokes model

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The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform $\mathrm{T}_{\delta}$-coercivity. Given finite dimensional subspaces $\left(\boldsymbol{V}_{\delta}\right)_{\delta}$ of $\boldsymbol{H}_{0}^{1}(\Omega)$, resp. $\left(Q_{\delta}\right)_{\delta}$ of $L_{z m v}^{2}(\Omega)$, one can build an approximation of the Stokes model. Question: how to choose them?

## Stokes model

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Mimic the previous proof to guarantee uniform $\mathrm{T}_{\delta}$-coercivity for the Stokes model!

## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 1

The discrete variational formulation writes
$(\text { FV-Stokes })_{\delta}\left\{\begin{array}{l}\text { Find }\left(\boldsymbol{u}_{\delta}, p_{\delta}\right) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \text { such that } \\ \forall\left(\boldsymbol{v}_{\delta}, q_{\delta}\right) \in \boldsymbol{V}_{\delta} \times Q_{\delta}, \\ \nu \int_{\Omega} \boldsymbol{\nabla} \boldsymbol{u}_{\delta}: \nabla \boldsymbol{v}_{\delta} d \Omega-\int_{\Omega} p_{\delta} \operatorname{div} \boldsymbol{v}_{\delta} d \Omega-\int_{\Omega} q_{\delta} \operatorname{div} \boldsymbol{u}_{\delta} d \Omega=\boldsymbol{H}^{-1}(\Omega)\left\langle\boldsymbol{f}, \boldsymbol{v}_{\delta}\right\rangle_{\boldsymbol{H}_{0}^{1}(\Omega)} .\end{array}\right.$

## Stokes model

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The discrete variational formulation writes
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Given $\left(\boldsymbol{v}_{\delta}, q_{\delta}\right) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \backslash\{(0,0)\}$, we look for $\left(\boldsymbol{w}_{\delta}^{\star}, r_{\delta}^{\star}\right) \in \boldsymbol{V}_{\delta} \times Q_{\delta} \backslash\{(0,0)\}$ such that

$$
\left|a\left(\left(\boldsymbol{v}_{\delta}, q_{\delta}\right),\left(\boldsymbol{w}_{\delta}^{\star}, r_{\delta}^{\star}\right)\right)\right| \geq \alpha_{\dagger}\left\|\left(\boldsymbol{v}_{\delta}, q_{\delta}\right)\right\|_{V}\left\|\left(\boldsymbol{w}_{\delta}^{\star}, r_{\delta}^{\star}\right)\right\|_{V},
$$

with $\alpha_{\dagger}>0$ independent of $\delta$ and of $\left(\boldsymbol{v}_{\delta}, q_{\delta}\right)$.

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$$

with $\alpha_{\dagger}>0$ independent of $\delta$ and of $\left(\boldsymbol{v}_{\delta}, q_{\delta}\right)$. Mimicking the T-coercivity approach, one chooses

$$
\boldsymbol{w}^{\star}=\nu\left(C_{\mathrm{div}}\right)^{2} \boldsymbol{v}_{\delta}-\boldsymbol{w}_{q_{\delta}} \text { and } r^{\star}=-\nu\left(C_{\mathrm{div}}\right)^{2} q_{\delta},
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$$
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with $\boldsymbol{w}_{q_{\delta}} \in \boldsymbol{H}_{0}^{1}(\Omega)$ such that $\operatorname{div} \boldsymbol{w}_{q_{\delta}}=q_{\delta}$, and $\left|\boldsymbol{w}_{q_{\delta}}\right|_{1, \Omega} \leq C_{\text {div }}\left\|q_{\delta}\right\|$.
Difficulty: $\boldsymbol{w}_{q_{\delta}} \notin \boldsymbol{V}_{\delta}$ in general, whereas $\boldsymbol{v}_{\delta} \in \boldsymbol{V}_{\delta}$ and $r^{\star} \in Q_{\delta}$.

## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 2

How to overcome this difficulty to be able to conclude the proof?


Find $\boldsymbol{w}_{\delta}^{+} \in \boldsymbol{V}_{\delta}$ such that $" \operatorname{div} \boldsymbol{w}_{\delta}^{+}=q_{\delta}$ ", and $\left|\boldsymbol{w}_{\delta}^{+}\right|_{1, \Omega} \leq C^{+}\left\|q_{\delta}\right\|$ with $C^{+}>0$ independent of $\delta, q_{\delta}$.

## Stokes model

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As a matter of fact, choosing $\boldsymbol{w}_{\delta}^{\star}=\nu\left(C^{+}\right)^{2} \boldsymbol{v}_{\delta}-\boldsymbol{w}_{\delta}^{+}$and $r_{\delta}^{\star}=-\nu\left(C^{+}\right)^{2} q_{\delta}$ immediately yields the uniform discrete inf-sup condition!

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## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 2

How to overcome this difficulty to be able to conclude the proof?

Find $\boldsymbol{w}_{\delta}^{+} \in \boldsymbol{V}_{\delta}$ such that $" \operatorname{div} \boldsymbol{w}_{\delta}^{+}=q_{\delta}$ ", and $\left|\boldsymbol{w}_{\delta}^{+}\right|_{1, \Omega} \leq C^{+}\left\|q_{\delta}\right\|$ with $C^{+}>0$ independent of $\delta, q_{\delta}$.

In other words, one is looking for pairs of discrete spaces $\left(\boldsymbol{V}_{\delta}, Q_{\delta}\right)_{\delta}$ such that

$$
\begin{aligned}
& \exists C_{\pi}>0, \forall \delta, \exists \pi_{\delta} \in \mathcal{L}\left(\boldsymbol{H}_{0}^{1}(\Omega), \boldsymbol{V}_{\delta}\right) \text { with the properties } \\
& \forall \boldsymbol{v} \in \boldsymbol{H}_{0}^{1}(\Omega), \quad\left|\pi_{\delta} \boldsymbol{v}\right|_{1, \Omega} \leq C_{\pi}|\boldsymbol{v}|_{1, \Omega} ; \\
& \forall \boldsymbol{v}
\end{aligned} \in \boldsymbol{H}_{0}^{1}(\Omega), \quad \forall q_{\delta}^{\prime} \in Q_{\delta}, \quad \int_{\Omega} q_{\delta}^{\prime} \operatorname{div}\left(\pi_{\delta} \boldsymbol{v}\right) d \Omega=\int_{\Omega} q_{\delta}^{\prime} \operatorname{div} \boldsymbol{v} d \Omega .
$$

to set $\boldsymbol{w}_{\delta}^{+}=\pi_{\delta} \boldsymbol{w}_{q_{\delta}}$

## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 2

How to overcome this difficulty to be able to conclude the proof?

${ }^{5}$ Find $\boldsymbol{w}_{\delta}^{+} \in \boldsymbol{V}_{\delta}$ such that ${ }^{\prime} \operatorname{div} \boldsymbol{w}_{\delta}^{+}=q_{\delta}$ ", and $\left|\boldsymbol{w}_{\delta}^{+}\right|_{1, \Omega} \leq C^{+}\left\|q_{\delta}\right\|$ with $C^{+}>0$ independent of $\delta, q_{\delta}$.

By browsing the book by Boffi-Brezzi-Fortin (2013), one finds that:

- the MINI finite element of order $k \geq 1$ does the job!


## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 2

How to overcome this difficulty to be able to conclude the proof?

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By browsing the book by Boffi-Brezzi-Fortin (2013), one finds that:

- the MINI finite element of order $k \geq 1$ does the job!
- the Taylor-Hood finite element of order $k \geq 1$ does the job!


## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 3
Regarding the proof with uniform $\mathrm{T}_{\delta}$-coercivity, one can make further observations:
(1) The so-called Fortin lemma appears "naturally" in the proof.
(2) One needs to have some knowledge of finite element spaces.
(3) The proof is "simple"!

## Stokes model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity - 3

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(1) The so-called Fortin lemma appears "naturally" in the proof.
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T-coercivity and uniform $\mathrm{T}_{\delta}$-coercivity are indeed strongly correlated for the Stokes model!

## Outline

## (1) What is T-coercivity?

(2) Stokes model
(3) Neutron diffusion model
(4) Further remarks
(5) Conclusion

Further remarks

## Neutron diffusion model

## The model

(1) Let $\Omega$ be a domain of $\mathbb{R}^{3}$. The basic brick of neutron diffusion writes

$$
\left\{\begin{array}{l}
-\operatorname{div} \mathbb{D} \nabla u+\sigma u=S_{f} \text { in } \Omega \\
u=0 \text { on } \partial \Omega
\end{array}\right.
$$

or, equivalently, with the additional unknown $\boldsymbol{p}=-\mathbb{D} \nabla u$,

$$
\left\{\begin{array}{l}
\operatorname{div} \boldsymbol{p}+\sigma u=S_{f} \text { in } \Omega \\
u=0 \text { on } \partial \Omega
\end{array}\right.
$$

for some uniformly positive symmetric tensor $\boldsymbol{x} \mapsto \mathbb{D}(\boldsymbol{x})$ (diffusion tensor), and uniformly positive $\boldsymbol{x} \mapsto \sigma(\boldsymbol{x})$ (macroscopic absorption cross section).

## Neutron diffusion model

(1) Assuming that $S_{f} \in L^{2}(\Omega)$, one analyses mathematically the model

$$
\text { (Diffusion) } \quad\left\{\begin{array}{l}
\text { Find }(u, \boldsymbol{p}) \in H_{0}^{1}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega) \text { such that } \\
\operatorname{div} \boldsymbol{p}+\sigma u=S_{f} \text { in } \Omega \\
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## Neutron diffusion model

## The model

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\end{array}\right.
$$

(2) After elementary manipulations, the equivalent variational formulation writes
(FV-Diffusion) $\left\{\begin{array}{l}\text { Find }(u, \boldsymbol{p}) \in L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega) \text { such that } \\ \forall(w, \boldsymbol{r}) \in L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega), \\ \int_{\Omega}\left(-\mathbb{D}^{-1} \boldsymbol{p} \cdot \boldsymbol{r}+u \operatorname{div} \boldsymbol{r}+w \operatorname{div} \boldsymbol{p}+\sigma u w\right) d \Omega=\int_{\Omega} S_{f} w d \Omega .\end{array}\right.$

## Neutron diffusion model

## The model

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(2) After elementary manipulations, the equivalent variational formulation writes
(FV-Diffusion) $\left\{\begin{array}{l}\text { Find }(u, \boldsymbol{p}) \in L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega) \text { such that } \\ \forall(w, \boldsymbol{r}) \in L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega), \\ \int_{\Omega}\left(-\mathbb{D}^{-1} \boldsymbol{p} \cdot \boldsymbol{r}+u \operatorname{div} \boldsymbol{r}+w \operatorname{div} \boldsymbol{p}+\sigma u w\right) d \Omega=\int_{\Omega} S_{f} w d \Omega .\end{array}\right.$
Question: how to prove well-posedness "easily"?

## Neutron diffusion model

## The model

(1) Assuming that $S_{f} \in L^{2}(\Omega)$, one analyses mathematically the model

$$
\text { (Diffusion) } \quad\left\{\begin{array}{l}
\text { Find }(u, \boldsymbol{p}) \in H_{0}^{1}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega) \text { such that } \\
\operatorname{div} \boldsymbol{p}+\sigma u=S_{f} \text { in } \Omega \\
\mathbb{D}^{-1} \boldsymbol{p}+\nabla u=0 \text { in } \Omega .
\end{array}\right.
$$

(2) After elementary manipulations, the equivalent variational formulation writes

$$
\text { (FV-Diffusion) }\left\{\begin{array}{l}
\text { Find }(u, \boldsymbol{p}) \in L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega) \text { such that } \\
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\end{array}\right.
$$

Question: how to prove well-posedness "easily"?

Use T-coercivity for the neutron diffusion model!

## Neutron diffusion model

Constructive proof of well-posedness with T-coercivity - 1

Let

- $V=L^{2}(\Omega) \times \boldsymbol{H}(\operatorname{div} ; \Omega)$, endowed with the norm $\|(v, \boldsymbol{q})\|_{V}=\left(\|v\|^{2}+\|\boldsymbol{q}\|_{\boldsymbol{H}(\operatorname{div} ; \Omega)}^{2}\right)^{1 / 2} ;$
- $a((v, \boldsymbol{q}),(w, \boldsymbol{r}))=-\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} d \Omega+\int_{\Omega} v \operatorname{div} \boldsymbol{r} d \Omega+\int_{\Omega} w \operatorname{div} \boldsymbol{q} d \Omega+\int_{\Omega} \sigma v w d \Omega$;
- ${ }_{V^{\prime}}\langle f, w\rangle_{V}=\int_{\Omega} S_{f} w d \Omega$.


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Constructive proof of well-posedness with T-coercivity - 1

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- ${ }_{V^{\prime}}\langle f, w\rangle_{V}=\int_{\Omega} S_{f} w d \Omega$.

Again, the first goal is to prove the inf-sup condition, with the help of T-coercivity.
NB. The form $a$ is not coercive, because $|a((0, \boldsymbol{q}),(0, \boldsymbol{q}))|=\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{q} d \Omega$ controls $\|\boldsymbol{q}\|^{2}$, but not $\|\boldsymbol{q}\|_{\boldsymbol{H}(\mathrm{div} ; \Omega)}^{2}$.

## Neutron diffusion model

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- ${ }_{V^{\prime}}\langle f, w\rangle_{V}=\int_{\Omega} S_{f} w d \Omega$.

Again, the first goal is to prove the inf-sup condition, with the help of T-coercivity. Given $(v, \boldsymbol{q}) \in V \backslash\{(0,0)\}$, we look for $\left(w^{\star}, \boldsymbol{r}^{\star}\right) \in V \backslash\{(0,0)\}$ with linear dependence such that

$$
\left|a\left((v, \boldsymbol{q}),\left(w^{\star}, \boldsymbol{r}^{\star}\right)\right)\right| \geq \alpha\|(v, \boldsymbol{q})\|_{V}\left\|\left(w^{\star}, \boldsymbol{r}^{\star}\right)\right\|_{V}
$$

with $\alpha>0$ independent of $(v, \boldsymbol{q})$.

## Neutron diffusion model

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Again, the first goal is to prove the inf-sup condition, with the help of T-coercivity. Given $(v, \boldsymbol{q}) \in V \backslash\{(0,0)\}$, we look for $\left(w^{\star}, \boldsymbol{r}^{\star}\right) \in V \backslash\{(0,0)\}$ with linear dependence such that

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$$

with $\alpha>0$ independent of $(v, \boldsymbol{q})$. Again, three steps:
(1) $\boldsymbol{q}=0$;
(2) $v=0$ and $\boldsymbol{q}$ such that $\operatorname{div} \boldsymbol{q}=0$;
(3) General case.

## Neutron diffusion model

Constructive proof of well-posedness with T-coercivity - 2
Recall $a((v, \boldsymbol{q}),(w, \boldsymbol{r}))=-\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} d \Omega+\int_{\Omega} v \operatorname{div} \boldsymbol{r} d \Omega+\int_{\Omega} w \operatorname{div} \boldsymbol{q} d \Omega+\int_{\Omega} \sigma v w d \Omega$.
One finds that (skipping the details)
(1) $a((v, 0),(w, \boldsymbol{r}))=\int_{\Omega} v \operatorname{div} \boldsymbol{r} d \Omega+\int_{\Omega} \sigma v w d \Omega$ : choose $\left(w^{\star}, \boldsymbol{r}^{\star}\right)=(v, 0)$.
(2) $a((0, \boldsymbol{q}),(w, \boldsymbol{r}))=-\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} d \Omega($ with $\operatorname{div} \boldsymbol{q}=0)$ : choose $\left(w^{\star}, \boldsymbol{r}^{\star}\right)=(0,-\boldsymbol{q})$.
(3) General case:

## Neutron diffusion model

Constructive proof of well-posedness with T-coercivity - 2
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(2) $a((0, \boldsymbol{q}),(w, \boldsymbol{r}))=-\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{r} d \Omega($ with $\operatorname{div} \boldsymbol{q}=0)$ : choose $\left(w^{\star}, \boldsymbol{r}^{\star}\right)=(0,-\boldsymbol{q})$.
(3) General case: beginning with $\boldsymbol{r}^{\star}=-\boldsymbol{q}$, one finds

$$
a\left((v, \boldsymbol{q}),\left(w, \boldsymbol{r}^{\star}\right)\right)=\int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{q} d \Omega+\int_{\Omega}(w-v) \operatorname{div} \boldsymbol{q} d \Omega+\int_{\Omega} \sigma v w d \Omega .
$$

## Neutron diffusion model

Constructive proof of well-posedness with T-coercivity - 2
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(3) General case: $\boldsymbol{r}^{\star}=-\boldsymbol{q}$. Next, $w^{\star}=\alpha\left(v+\sigma^{-1} \operatorname{div} \boldsymbol{q}\right), \alpha>0$ leads to

$$
\begin{aligned}
a\left((v, \boldsymbol{q}),\left(w^{\star}, \boldsymbol{r}^{\star}\right)\right)= & \int_{\Omega} \mathbb{D}^{-1} \boldsymbol{q} \cdot \boldsymbol{q} d \Omega+\int_{\Omega} \sigma^{-1}(\operatorname{div} \boldsymbol{q})^{2} d \Omega+\alpha \int_{\Omega} \sigma v^{2} d \Omega \\
& +(2 \alpha-1) \int_{\Omega} v \operatorname{div} \boldsymbol{q} d \Omega
\end{aligned}
$$

## Neutron diffusion model

Constructive proof of well-posedness with T-coercivity - 2
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& +(2 \alpha-1) \int_{\Omega} v \operatorname{div} \boldsymbol{q} d \Omega
\end{aligned}
$$

So, choosing $\left(w^{\star}, \boldsymbol{r}^{\star}\right)=\left(\frac{1}{2}\left(v+\sigma^{-1} \operatorname{div} \boldsymbol{q}\right),-\boldsymbol{q}\right)$ yields T-coercivity.

## Neutron diffusion model

Constructive proof of convergence with uniform $\mathrm{T}_{\delta}$-coercivity

We assume that $\sigma$ is constant (general case, see PC-Jamelot-Kpadonou'17). The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform $\mathrm{T}_{\delta}$-coercivity. Given finite dimensional subspaces $\left(V_{\delta}\right)_{\delta}$ of $L^{2}(\Omega)$, resp. $\left(\boldsymbol{Q}_{\delta}\right)_{\delta}$ of $\boldsymbol{H}(\operatorname{div} ; \Omega)$, one can build an approximation of the neutron diffusion model. Question: how to choose them?


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$$
\left|a\left(\left(v_{\delta}, \boldsymbol{q}_{\delta}\right),\left(w_{\delta}^{\star}, \boldsymbol{r}_{\delta}^{\star}\right)\right)\right| \geq \alpha_{\dagger}\left\|\left(v_{\delta}, \boldsymbol{q}_{\delta}\right)\right\|_{V}\left\|\left(w_{\delta}^{\star}, \boldsymbol{r}_{\delta}^{\star}\right)\right\|_{V},
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with $\alpha_{\dagger}>0$ independent of $\delta$ and of $\left(v_{\delta}, \boldsymbol{q}_{\delta}\right)$.

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with $\alpha_{\dagger}>0$ independent of $\delta$ and of $\left(v_{\delta}, \boldsymbol{q}_{\delta}\right)$. Mimicking the T-coercivity approach, one chooses

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w^{\star}=\frac{1}{2}\left(v_{\delta}+\sigma^{-1} \operatorname{div} \boldsymbol{q}_{\delta}\right) \text { and } \boldsymbol{r}^{\star}=-\boldsymbol{q}_{\delta} .
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Difficulty: $\operatorname{div} \boldsymbol{q}_{\delta} \in V_{\delta}$ ? Whereas $v_{\delta} \in V_{\delta}$ and $\boldsymbol{q}_{\delta} \in \boldsymbol{Q}_{\delta}$.

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By browsing the book by Boffi-Brezzi-Fortin (2013), one finds that: the Raviart-Thomas finite element of order $k \geq 0$ does the job!

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The second goal is to prove the uniform discrete inf-sup condition, with the help of the uniform $\mathrm{T}_{\delta}$-coercivity. Given finite dimensional subspaces $\left(V_{\delta}\right)_{\delta}$ of $L^{2}(\Omega)$, resp. $\left(\boldsymbol{Q}_{\delta}\right)_{\delta}$ of $\boldsymbol{H}(\operatorname{div} ; \Omega)$, one can build an approximation of the neutron diffusion model. Question: how to choose them? Given $\left(v_{\delta}, \boldsymbol{q}_{\delta}\right) \in V_{\delta} \times \boldsymbol{Q}_{\delta} \backslash\{(0,0)\}$, we look for $\left(w_{\delta}^{\star}, \boldsymbol{r}_{\delta}^{\star}\right) \in V_{\delta} \times \boldsymbol{Q}_{\delta} \backslash\{(0,0)\}$ such that

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By browsing the book by Boffi-Brezzi-Fortin (2013), one finds that:
the Raviart-Thomas finite element of order $k \geq 0$ does the job!
The proof is again very "simple"!

## Further remarks

Possible extensions:
(1) T-coercivity still usable with the Strang lemmas (approximate forms).
(2) Stokes model: see Jamelot'22 for a non-conforming discretisation (Crouzeix-Raviart or Fortin-Soulié finite elements); see master's thesis by MRoueh' 22 for DG discretisation ; see Barré-Grandmont-Moireau'22 for a poromechanics model.
(3) diffusion model: see PC-Jamelot-Kpadonou'17 or PC-Giret-Jamelot-Kpadonou'18 for Domain Decomposition (DDM $+L^{2}$-jumps).
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NB. For the electrostatic model, one recovers the Nédélec finite element.

## Conclusion

Within the framework of T-coercivity, analysing a variational formulation theoretically and solving it numerically are very strongly correlated issues!

## Conclusion

Within the framework of T-coercivity, analysing a variational formulation theoretically and solving it numerically are very strongly correlated issues!
[IN PROGRESS] (with Mathieu Barré) Study of abstract mixed variational formulations, and "simplification/extensions" of results in the book by Boffi-Brezzi-Fortin (2013).
[TO DO] Investigate how T-coercivity could be extended to formulations set in Banach spaces (using eg. Arendt-Chalendar-Eymard'20).

Thank you for your attention!

